



Nodeu J1939

#### **FEATURES**

Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT) SSI, CANopen<sup>®</sup>, or SAE J1939 communication Maintenance-free and environmentally friendly magnetic design Energy harvesting magnetic multi-turn technology No gears or batteries IP67 sealing available Servo and flange mounting Standard Size 25 package (2.5" x 2.5") Meets CE/EMC standards for immunity and emissions

The Model A25SB absolute encoder offers a high performance solution for your absolute feedback needs. This encoder is especially suited for applications where position information must be retained after loss of system power. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is the perfect choice for harsh industrial applications thanks to its rugged magnetic technology, available IP67 rating, and proven double bearing design. Available with several shaft sizes and mounting styles, the Model A25SB is easily designed into OEM and aftermarket applications.

#### **COMMON APPLICATIONS**

Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Heavy Duty Vehicles, Cranes, Rotary and X/Y Positioning Tables

Model	Mechan	ical				Electrical					Environmental
A25SB —	10	MA – 1	2 1	0	со	A	B	V2 -	RMJ	-	- NR -
MODEL 5SB Absolute Series	MA	<b>INTING TYPE</b> 2.50" Flange 2.50" Servo mount	RESOL 00	I-TURN UTION <sup>1</sup> Single Turn Multi-Turn	A	SOFTWARE REV Revision A	INF 5 V2	5 VDC <sup>5</sup> 5 to 32 VDC		<b>TEMF</b> 0° to 80 -40° to 8	° C (Std)
SHA	FT SIZE	SINGLE TUR	N CC	OMMUNICATI	ON	OUTPUT CO	DE	CONNECTO	R TYPE <sup>6</sup>	Т	ERMINATING RESISTOR <sup>7</sup>
<b>10</b> 10 <b>A9</b> 3/	) mm 8", 0.375" 4", 0.250"	RESOLUTION 01 to 16 Bit	4 <sup>1</sup>	PROTOCOL CANopen <sup>2</sup> SAE J1939 <sup>1,3</sup> SSI <sup>4</sup>		B Binary G Gray <sup>5</sup>		J 5-pin M12 K 8-pin M12		RS In	one (Std) ternal resistor ixed 120 Ohm)

- 3 Please refer to Technical Bulletin TB-546: SAE J1939 Interface and Process Data at encoder.com.
- 4 Please refer to Technical Bulletin TB-529: Understanding EPC's SSI Encoders at encoder.com.
- 5 Available with SSI only.
- For mating connectors, cables, and cordsets see Accessories at encoder.com. For Connector Pin Configuration Diagrams, see Technical Information or see Connector Pin Configuration Diagrams 6 at encoder.com.
- Available with CANopen and SAE J1939 only.

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#### Electrical

Input Voltage	5 to 32 VDC max 5 VDC SSI Only
Input Current	50 mA typical for 5 to 32 VDC 80 mA typical for 5 VDC
Power Consumption	0.5 W max
Resolution (Single)	01 to 16 bit
Resolution (Multi)	01 to 43 bit
Accuracy	<±0.0878°
Repeatability	<±0.0878°
CE/EMC	Immunity tested per EN 61000-6-2:2006 Emissions tested per EN 61000-6-3:2011

#### Mechanical

Max Shaft Speed	8000 RPM
Shaft Material	303 Stainless Steel
Radial Shaft Load	Bearing life of 1.5x10 <sup>9</sup> revolutions: 80lbs (355 N) max. rated load of 20 to 40lbs (88 to 177 N)
Axial Shaft Load	Bearing life of 1.5x10 <sup>9</sup> revolutions: 80lbs (355 N) max. rated load of 20 to 40lbs (88 to 177 N)
Starting Torque	Bearing life of 1.4x10 <sup>8</sup> revolutions: 11lbs (50 N)
Starting Torque	1.0 oz-in typical with no seal 3.0 oz-in typical with IP66 shaft seal 7.0 oz-in typical with IP67 shaft seal
Housing	Black non-corrosive finish
Weight	20 oz typical

#### Environmental

Storage Temp	-40° C to 100° C	
Humidity	95% RH non-condensing	
Vibration	30.6 g (10 Hz up to 2000 Hz)	
Shock	510 g @ 6 ms duration	
Sealing	IP50, standard; IP66 or IP67, optional	

#### **CANopen Interface**

Protocol	CANopen	
	Communication profile CiA 301	
	Device profile for encoder CiA 406 V3.2 class C2	
Node Number	0 to 127 (default 127)	
Baud Number	10 Kbaud to 1 Mbaud with automatic bit rate detection	
	ngs as well as any customization in the software can be i) and the SDO protocol (e.g. PDOs, scaling, heartbeat, node-	

#### Programmable CANopen Transmission Modes

Synchronis	When a synchornization telegram (SYNC) is received from another bus node, PDOs are transmitted independently				
		message is triggered by an internal event (e.g. of measured value, internal timer, etc.)			
SAE J1939					
CAN physical layer		ISO 11898 (High Speed CAN)			
Protocol		ISO 11898 (High Speed CAN)			
Baud Rate		Auto-Baud-Detection			
Standard Preset configuration		(other configurations on request)			
Direction of counting		CCW (view from shaft end)			
ECU-address		0x0A			
Process data Identifier		0x18FF000A			
PGN		0xFF00			
Process data mapping		Byte 0-3 32 Bit Position Value			
		Byte 4 8 Bit Error Register			
		PDU timer and Position Preset can be adjusted by PGN configuration 0xEF00 (Prop. A)			
PDU - Time		50ms (default)			
Configuration - PGN		0xEF 00 (Prop. A)			
Byte 0		0x01			
Byte 1		0xFF			
Byte 2		PDU time LSB			
Byte 3		PDU time MSB			
Byte 4		Preset LSB			
Byte 5,6		Preset			
Byte 7		Preset MSB			

#### SSI Interface

Clock Input	Via opto coupler
Clock Frequency	100Kz to 500Kz, Higher frequencies may be available. Contact Customer Service.
Data Output	RS485/RS422 compatible
Output Code	Gray or binary
SSI Output	Angular position value
Parity Bit	Optional (even/odd)
Error Bit	Optional
Turn On Time	< 1.5 sec
Pos Counting Dir	Connect DIR to GND for CW
	Connnect DIR to VDC for CCW
	(when viewed from shaft end)
Set to Zero	Yes, see Technical Bulletin TB529: Understanding EPC's SSI Encoders
Protection	Galvanic Isolation with SSI option



#### MODEL A25SB 2.5" FLANGE MOUNT (MA)





MODEL A25SB 2.5" SERVO MOUNT (MC)







Primary dimensions are in inches, secondary dimensions [mm] in brackets for reference only.



#### WIRING TABLE

For EPC-supplied mating cables, refer to wiring table provided with cable.

For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires.

# **SSI Encoders** 8-pin M12



Function	Pin
Ground (GND)	1
+VDC	2
SSI CLK+	3
SSI CLK-	4
SSI DATA+	5
SSI DATA-	6
PRESET	7
DIR	8
Shield	Housing

CANopen and
SAE J1939
Encoders

