



Ø36 mm





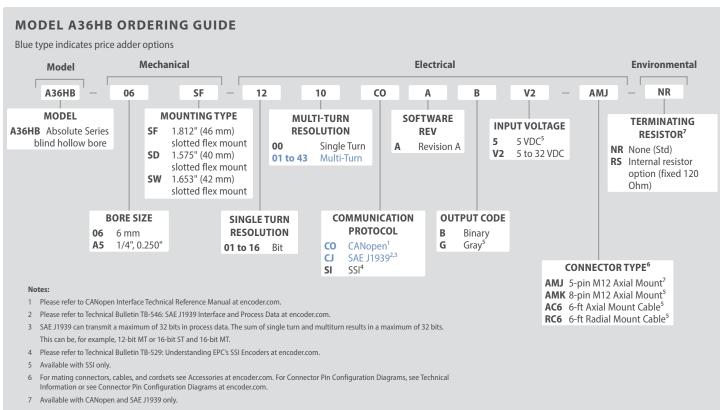
#### **FEATURES**

Single Turn/Multi-Turn Absolute Encoder (16 Bit ST / 43 Bit MT)
SSI, CANopen®, or SAE J1939 communication
Maintenance-free and environmentally friendly all-magnetic design
Energy harvesting magnetic multi-turn technology
No gears or batteries
Standard Size 36 mm (1.42") blind hollow bore encoder
Flex mount eliminates couplings and is ideal for motors or shaft
Meets CE/EMC standards for immunity and emissions

The Model A36HB absolute encoder offers a high performance solution for your absolute feedback needs. It provides maintenance-free feedback thanks to its innovative battery-free and gear-free multi-turn technology. This encoder is especially suited for applications where position information must be retained after loss of system power. Its rugged magnetic technology and high IP rating make the Model A36HB an excellent choice, even in tough industrial environments. Available with a 1/4" or 6 mm blind hollow bore and a wide selection of flexible mounting options, the Model A36HB is easily designed into a variety of applications.

#### **COMMON APPLICATIONS**

Robotics, Telescopes, Antennas, Medical Scanners, Wind Turbines, Elevators, Lifts, Motors, Automatic Guided Vehicles, Heavy Duty Vehicles, Cranes, Rotary and X/Y Positioning Tables



EPC RESERVES THE RIGHT TO UPDATE, REVISE AND AMEND ALL SOFTWARE AND TECHNICAL DATA OR CONTENT AT ANY TIME. EPC SHALL HAVE NO LIABILITY OF ANY KIND OR NATURE FOR ANY TECHNICAL ERRORS OR OMISSIONS IN ANY SOFTWARE OR TECHNICAL DATA.

See encoder.com for more information.



#### **Electrical**

Input Voltage	5 to 32 VDC max 5 VDC SSI Only
Input Current	50 mA typical for 5 to 32 VDC 80 mA typical for 5 VDC
Power Consumption	0.5 W max
Resolution (Single)	01 to 16 bit
Resolution (Multi)	01 to 43 bit
Accuracy	<±0.0878°
Repeatability	<±0.0878°
CE/EMC	Immunity tested per EN 61000-6-2:2006 Emissions tested per EN 61000-6-3:2011

#### Mechanical

Max Shaft Speed	12000 RPM
Bore Depth	17mm (0.669")
User Shaft Radial Runout	0.005" max
Radial Shaft Load	Bearing life of 1.4x10 <sup>8</sup> revolutions: 17lbs (80 N)
Axial Shaft Load	Bearing life of 1.4x10 <sup>8</sup> revolutions: 11lbs (50 N)
Starting Torque	< 0.45oz-in typical
Housing	All metal with protective finish
Weight	5 oz typical

#### **Environmental**

Operating Temp	-40° C to 85° C
Storage Temp	-40° C to 100° C
Humidity	95% RH non-condensing
Vibration	30.6 g (10 Hz up to 2000 Hz)
Shock	510 g @ 6 ms duration
Sealing	IP67 , shaft sealed to IP65

### **CANopen Interface**

Protocol	CANopen
	Communication profile CiA 301
	Device profile for encoder CiA 406 V3.2 class C2
Node Number	0 to 127 (default 127)
Baud Number	10 Kbaud to 1 Mbaud with automatic bit rate detection
	ngs as well as any customization in the software can be and the SDO protocol (e.g. PDOs, scaling, heartbeat, node-

### **Programmable CANopen Transmission Modes**

Synchronis	When a synchornization telegram (SYNC) is received from another bus node, PDOs are transmitted independently
Asynchronis	A PDO message is triggered by an internal event (e.g. change of measured value, internal timer, etc.)

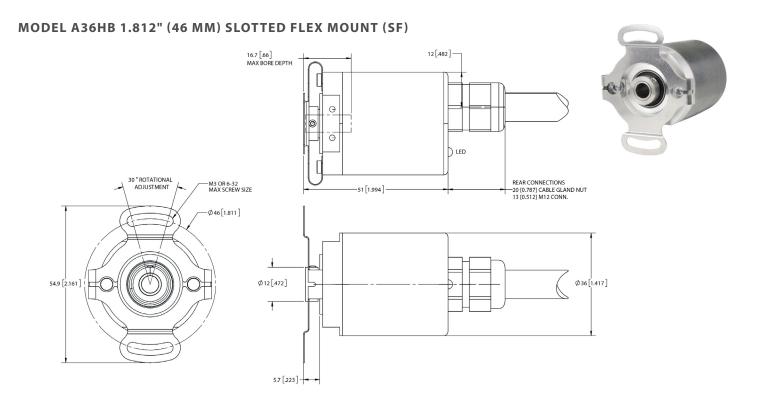
#### **SAE J1939**

3AE 31333	
CAN physical layer	ISO 11898 (High Speed CAN)
Protocol	ISO 11898 (High Speed CAN)
Baud Rate	Auto-Baud-Detection
Standard Preset configuration	(other configurations on request)
Direction of counting	CCW (view from shaft end)
ECU-address	0x0A
Process data Identifier	0x18FF000A
PGN	0xFF00
Process data mapping	Byte 0-3 32 Bit Position Value
	Byte 4 8 Bit Error Register
	PDU timer and Position Preset can be adjusted by PGN configuration 0xEF00 (Prop. A)
PDU - Time	50ms (default)
Configuration - PGN	0xEF 00 (Prop. A)
Byte 0	0x01
Byte 1	0xFF
Byte 2	PDU time LSB
Byte 3	PDU time MSB
Byte 4	Preset LSB
Byte 5, 6	Preset
Byte 7	Preset MSB

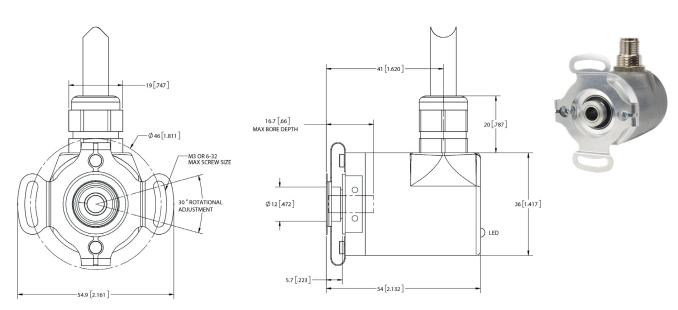
#### **SSI Interface**

Clock Input	Via opto coupler
Clock Frequency	100Kz to 500Kz, Higher frequencies may be available. Contact Customer Service.
Data Output	RS485/RS422 compatible
Output Code	Gray or binary
SSI Output	Angular position value
Parity Bit	Optional (even/odd)
Error Bit	Optional
Turn On Time	< 1.5 sec
Pos Counting Dir	Connect DIR to GND for CW Connnect DIR to VDC for CCW (when viewed from shaft end)
Set to Zero	Yes, see Technical Bulletin TB529: Understanding EPC's SSI Encoders
Protection	Galvanic Isolation with SSI option





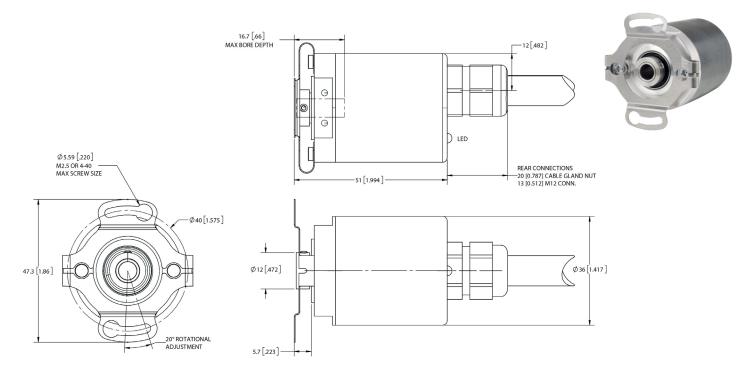
### MODEL A36HB 1.812" (46 MM) (SF) RADIAL



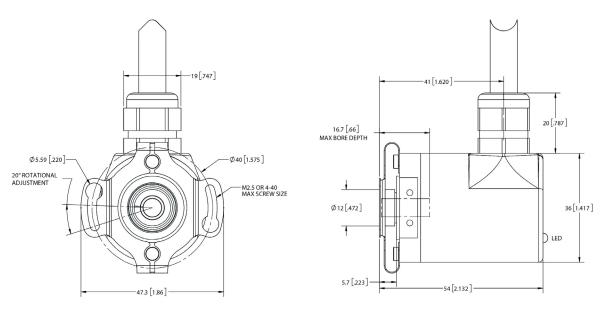
Primary dimensions are in mm, secondary dimensions [inches] in brackets for reference only.



# 1.575" (40 MM) SD AXIAL



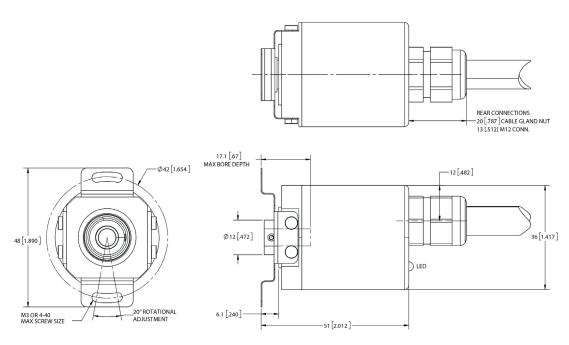
# 1.575" (40 MM) SD RADIAL



Primary dimensions are in mm, secondary dimensions [inches] in brackets for reference only.

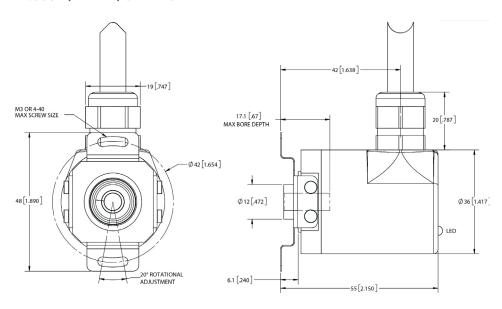


# 1.653" (42 MM) SW AXIAL





# 1.653" (42 MM) SW RADIAL



Primary dimensions are in mm, secondary dimensions [inches] in brackets for reference only.



#### **WIRING TABLE**

For EPC-supplied mating cables, refer to wiring table provided with cable. For CE (Conformity European) requirements, use M12 cordset with shield connected to M12 coupling nut. Trim back and insulate unused wires.

# **SSI Encoders** Flying Lead

**Function** 

+VDC

SSI CLK+

SSI CLK-

SSI DATA+

SSI DATA-

PRESET

DIR

Shield

shield.

Ground (GND)



**Gland cable** 

wire color\*

White

Brown

Yellow

Gray

Pink

Blue

Red

\*Standard cable is 24 AWG conductors with foil and braid

Side-exit

housing End-Exit N/C

1200	3/	
(2° °)	B°7) )	
450	9/	
\	/	

Function	8-Pin M12
Ground (GND)	1
+VDC	2
SSI CLK+	3
SSI CLK-	4
SSI DATA+	5
SSI DATA-	6
PRESET	7
DIR	8

**SSI Encoders** 8-pin M12

Shield

CANopen and
<b>SAE J1939</b>
Encoders
5-pin M12

Function

Ground (GND)

 $\mathsf{CAN}_\mathsf{GND}$  / Shield

+VDC

 $\mathsf{CAN}_{\mathsf{High}}$ 

 $\mathsf{CAN}_{\mathsf{Low}}$ 



Pin

2

3

4

5

Function	8-Pin M12
Ground (GND)	1
+VDC	2
SSI CLK+	3
SSI CLK-	4
SSI DATA+	5
SSI DATA-	6
PRESET	7

Housing